

KINEMATICS -I

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|-----|---|-----|---|-----|---|-----|---|-----|---|
| 1. | C | 2. | C | 3. | C | 4. | A | 5. | B |
| 6. | D | 7. | C | 8. | C | 9. | B | 10. | C |
| 11. | A | 12. | A | 13. | C | 14. | B | 15. | B |
| 16. | A | 17. | D | 18. | B | 19. | C | 20. | A |

MOLE CONCEPT

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|-----|---|-----|---|-----|---|-----|---|-----|---|
| 1. | A | 2. | D | 3. | A | 4. | A | 5. | C |
| 6. | C | 7. | C | 8. | C | 9. | D | 10. | C |
| 11. | B | 12. | B | 13. | C | 14. | B | 15. | C |
| 16. | C | 17. | B | 18. | D | 19. | C | | |

TRIGONOMETRY

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|-----|---|-----|---|-----|---|-----|---|-----|---|
| 1. | B | 2. | B | 3. | A | 4. | A | 5. | A |
| 6. | B | 7. | A | 8. | A | 9. | C | 10. | A |
| 11. | B | 12. | A | 13. | C | 14. | A | 15. | A |
| 16. | B | 17. | C | 18. | C | 19. | B | 20. | B |